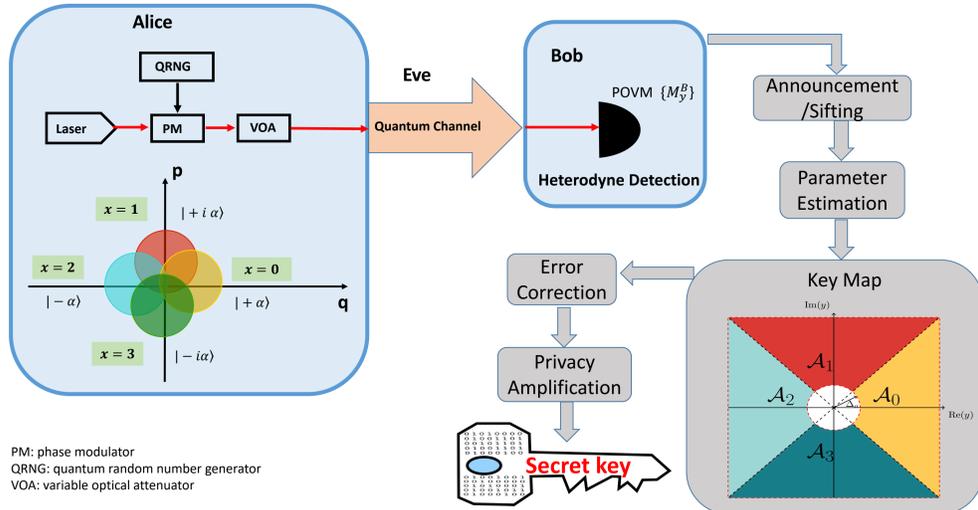


# Security Analysis of Discrete-Modulated Continuous-Variable Quantum Key Distribution

## INTRODUCTION

Discrete-modulated continuous-variable (CV) quantum key distribution (QKD) can be a cost-effective solution to distributing secret keys in the quantum-secured networks since it uses a setup nearly identical to modern telecommunication equipment.

## PROTOCOL DESCRIPTION



## SECURITY PROOF METHOD

Source-replacement scheme:

$$|\Psi\rangle_{AA'} = \sum_x \sqrt{p_x} |x\rangle_A |\alpha_x\rangle_{A'}$$

where Alice prepares  $|\alpha_x\rangle$  with a priori probability  $p_x$ , and  $\{|x\rangle\}$  is an orthonormal basis for the register A.

$\rho_{AB} = (id_A \otimes \mathcal{E}_{A' \rightarrow B})(|\Psi\rangle\langle\Psi|_{AA'})$ , where  $\mathcal{E}_{A' \rightarrow B}$  is a completely positive trace preserving (CPTP) map.

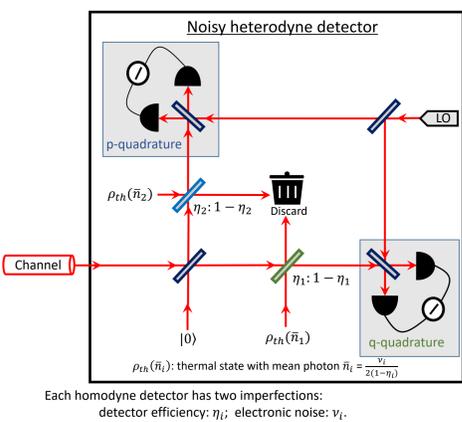
Asymptotic key rate (reverse reconciliation):

$$\begin{aligned} R^\infty &= p_{\text{pass}}(\beta I(\mathbf{X}; \mathbf{Z}) - \max_{\rho \in \mathcal{S}} \chi(\mathbf{Z}; \mathbf{E})) && \text{Devetak-Winter formula [3]} \\ &= p_{\text{pass}}(\min_{\rho \in \mathcal{S}} H(\mathbf{Z}|\mathbf{E}) - H(\mathbf{Z}) + \beta I(\mathbf{X}; \mathbf{Z})) && \text{Rewriting } \chi(\mathbf{Z}; \mathbf{E}) \\ &= \min_{\rho_{AB} \in \mathcal{S}} D(\mathcal{G}(\rho_{AB}) || \mathcal{Z}(\mathcal{G}(\rho_{AB}))) - p_{\text{pass}} H(\mathbf{Z}) + p_{\text{pass}} \beta I(\mathbf{X}; \mathbf{Z}) && \text{Ref. [4]} \end{aligned}$$

where the cost of error correction per signal is  $H(\mathbf{Z}) - \beta I(\mathbf{X}; \mathbf{Z})$ .

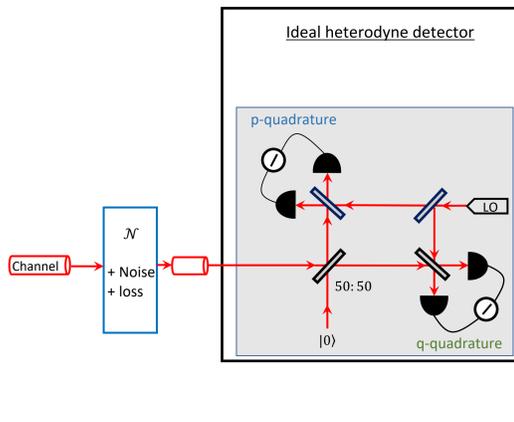
## DETECTOR MODEL

### Trusted Detector Noise



POVM: a (scaled) projection onto displaced squeezed thermal states

### Untrusted Detector Noise



POVM: a (scaled) projection onto coherent states

## OUR CONTRIBUTION

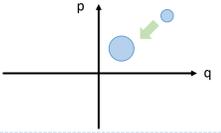
- Asymptotic security proofs against collective attacks
- Both untrusted and trusted detector noise scenarios
- Allowing postselection of data
- Can handle different variants of the protocol:
  - homodyne/ heterodyne
  - general discrete modulation schemes (not restricted to four)

## SIMULATION METHOD

Channel simulation

A phase-invariant Gaussian channel with
 

- transmittance  $\eta_t$
- excess noise  $\xi$  referred to input of the channel



Detector simulation

Two homodyne detectors have the same imperfections: detector efficiency:  $\eta_d := \eta_1 = \eta_2$ ; electronic noise:  $v_{el} := v_1 = v_2$ .

## SIMULATION RESULTS

### Ideal detector scenario

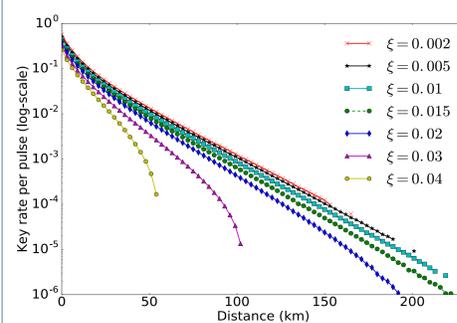


Fig. 7 of Ref. [1]. Key rate vs. transmission distance for different values of excess noise, from top to bottom,  $\xi = 0.002, 0.005, 0.01, 0.015, 0.02, 0.03, 0.04$ . Error correction efficiency  $\beta = 95\%$ . Coherent state amplitude  $\alpha$  is optimized via a coarse-grained search. ( $\eta_d=1, v_{el}=0$ )

### Trusted detector scenario

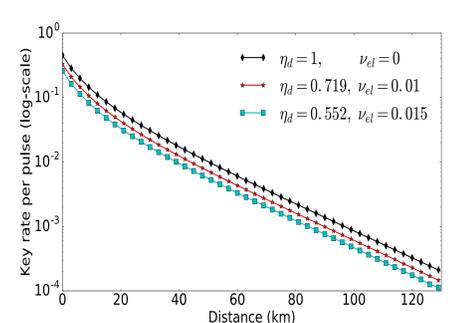


Fig. 4 of Ref. [2]. Key rate vs. transmission distance for different detector imperfections. The excess noise is  $\xi = 0.01$ . Error correction efficiency  $\beta = 95\%$ . Coherent state amplitude  $\alpha$  is optimized via a coarse-grained search.

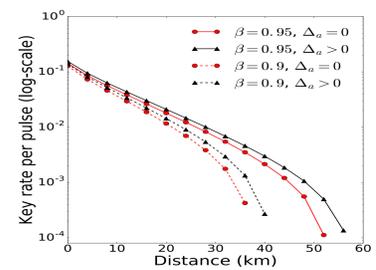


Fig. 10 (b) of Ref. [1]. Key rate vs. transmission distance for postsselection. The relevant postsselection parameter  $\Delta_a$  is optimized via a coarse-grained search in the interval  $[0.4, 0.7]$  where the optimal value falls.  $\alpha = 0.6, \xi = 0.04$ . ( $\eta_d=1, v_{el}=0$ )

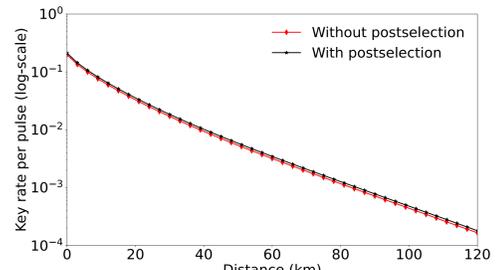
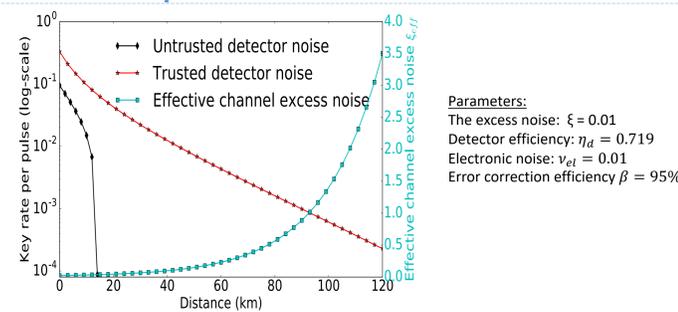


Fig. 8 of Ref. [2]. Key rate vs. transmission distance for postselection. Detector parameters are  $\eta_d=0.552, v_{el}=0.015$ . The relevant postsselection parameter  $\Delta_a$  is optimized via a coarse-grained search in the interval  $[0.45, 0.7]$ .  $\alpha = 0.75, \xi = 0.01$ . Error correction efficiency  $\beta = 95\%$ .

Comparison between trusted and untrusted detector noise scenarios



Two scenarios with the same observed statistics. Fig. 3 of Ref. [2]. Coherent state amplitude  $\alpha$  is optimized.

## KEY RATE OPTIMIZATION PROBLEM

Constraint formulation:

$$P(y|x) = \text{Tr}(\rho_x M_y^B) \xrightarrow{\text{Data processing}} \int f(y, y^*) P(y|x) d^2 y \xleftrightarrow{\text{General observables}} \hat{\sigma} = \int f(y, y^*) M_y^B d^2 y$$

where  $f(y, y^*)$  is a real-valued function such that the integral converges.

Nonlinear semidefinite program:

minimize  $D(\mathcal{G}(\rho_{AB}) || \mathcal{Z}(\mathcal{G}(\rho_{AB})))$   
subject to:

$$\begin{aligned} \text{Tr}[\rho_{AB} (|x\rangle\langle x|_A \otimes \hat{\sigma}_i)] &= p_x \langle \sigma_i \rangle_x \\ \text{Tr}_B[\rho_{AB}] &= \sum_{i,j=0}^3 \sqrt{p_i p_j} \langle \alpha_j | \alpha_i \rangle |i\rangle\langle j|_A \\ \rho_{AB} &\geq 0, \text{Tr}[\rho_{AB}] = 1 \end{aligned}$$

for  $x \in \{0, 1, 2, 3\}$  and some choices of  $\hat{\sigma}_i$

Examples of  $f(y, y^*)$ :  
 $\text{Re}(y), \text{Im}(y), yy^* - 1$

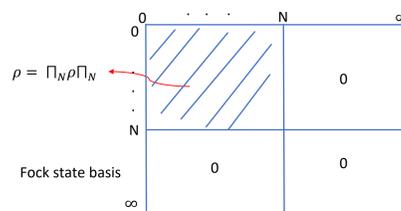
Examples of  $\hat{\sigma}_i$ :  
Quadrature operators  $\hat{q}$  and  $\hat{p}$   
Photon-number operator  $\hat{n}$

Region operators:  $R_j = \int_{y \in \mathcal{A}_j} M_y^B d^2 y$ .

$\mathcal{G}(\sigma) = K \sigma K^\dagger$ , where  $K$  is defined as  $K = \sum_{z=0}^3 |z\rangle_R \otimes 1_A \otimes (\sqrt{R_z})_B$   
 $\mathcal{Z}(\sigma) = \sum_{j=0}^3 Z_j \sigma Z_j$ , where  $Z_j = |j\rangle\langle j|_R \otimes 1_{AB}$  for  $j \in \{0, 1, 2, 3\}$ .

## PHOTON-NUMBER CUTOFF ASSUMPTION

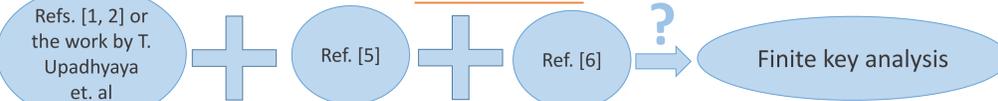
Assume  $\rho_{AB} = (1_A \otimes \Pi_N) \rho_{AB} (1_A \otimes \Pi_N)$  for a sufficiently large integer N.



Intuition of the cutoff assumption: When mean photon number  $n \ll N$ , essential information is captured in  $\leq N$  subspace

See poster by Twesh Upadhyaya for removing this assumption

## OUTLOOK



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